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Power OFF in Emergencies When abnormal noise, smoke, heat or odor occur, turn the power OFF immediately and unplug the power cord. As it may cause injury, be careful not to get clothing ties, long hair, etc. caught in the machine. If this happens, turn the power OFF immediately. Also, do not insert your fingers in the feed section while feeding documents. 2.

Electromagnetic Interference Countermeasures This machine complies with the electromagnetic interference standards VCCI A, FCCA, etc.. However, the user may have to carry out separate countermeasures if the machine causes electromagnetic interference. Do not change or modify this machine's specifications. If this has been carried out, its use may be forcibly discontinued on site. If the machine is disassembled and reassembled, follow the instructions described in this manual or in the Service Information Bulletins. This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions 1 This device may not cause harmful interference, and 2 this device must accept any interference received, including interference that may cause undesired operation. This Class A digital apparatus meets all requirements of the Canadian Interference Causing Equipment Regulations. Cet appareil numérique de la classe A respecte toutes les exigences du Règlement sur le matériel brouilleur du Canada. CAUTION LABEL 120 V machines 3. Users Manual Read the users manual thoroughly before using this machine. 4. Ink Cartridge Obey the handling instruction written in the package of the ink cartridge. 5. Disposal When disposing of the products and parts, obey local regulations. For the details, refer to the users manual. 1. Exterior Wipe the covers with a cloth tightly wrung with water or neutral detergent soaked, and then wipe dry. 2.

<http://www.drupalitalia.org/node/79210>

Document Sensor Take off the dusts gathered on the document sensors with a blower or equivalent. 3. Reading glass Wipe the reading glass Upper, Lower with a cloth tightly wrung with water and then wipe dry. 4. Feeder Assembly Wipe the following rollers with a cloth tightly wrung with water and then wipe dry 1 Pick up roller 2 Feed roller 3 Retard roller 4 Platen roller 5 Feeder roller 5. Cleaning of Shading plates Even when the reading glass and the rollers are cleaned, if the

s can ned im age is streak ed, the shading p late m ay be stain ed. W ipe the shading pl ates U pper, L ower with a cloth t ightl y wrung with water and t hen wipe dr y. Note Since the m achine is b eing turned ON, be caref ul to procee d the work. And, tak e car e so that the shading plates m ay not creased. 6. Po wer Cord After the p ower cor d is plu gged in to the outlet for a long p eriod of tim e, dust will coll ect on t he connecte d part an d cou ld cause a f ire or electr ic shocks. To p revent th is, clea n it reg u larly. 7. Imprinter guide plate If ink adheres to the guide plate loc ated in the inner par t of the im pr inter, it m a y contam inate the docum ent during scann ing op eration. W ipe the guide plate with a cloth t ightl y wrung with water or neutral det ergent s soaked, and th en wipe dr y. T o prevent t his, cl ean it r egula rl y. 8. Imprinter ink ca rtridge W ipe softl y the i nk adher ed to th e ink nozzle of the ink c artridges with a lintf ree cloth or paper A cotto ntipped s wab is also ac ceptab le. Be caref ul not to wipe or touc h the electr ical con tact part when wiping the ink. Im age pr ocessor Controls the rea ding s ystem, proc esses the im age data f rom the readi ng system, and outputs the d ata to the persona l com puter. Feed co ntroller Contr ols the f eed s ystem and im age proces sor.

<https://duluthtaxiservice.com/images/bravia-kdl40v2500-manual.pdf>

T able 2101 T he docum ent tra y contr ol PCB assem bly controls the doc um ent tray base d on signals from the m ain CPU PCB ass em bly and the pick up contro l PCB. Option Mechanical counter CNT1 Feed motor Pickup motor M3 M2 PS7 PS9 PS2 PS3 SL2 F ront registration L sensor F ront registration R sensor F ront registration sensor PCB Pickup sensor Imprinter door sensor Back registration sensor PS Back registration sensor PCB Shading solenoid Upper side Upper unit door sensor PS5 PS6 PS10 Leftend sensor Rightend sensor Leftend sensor PCB Rightend sensor PCB Pickup control PCB 0SUB Pickup solenoid SL1 Imprinter PCB Option Endorser Option P ower s witch SW 1 DC power supply PCB Main CPU PCB MAINDCON Ultrasonic sensor PCB USS1 Ultrasonic receiving sensor Ultrasonic drive PCB USS2 Ultrasonic transmitting sensor F ront reading unit Back reading unit Operation panel PCB FM1 M1 Ehaust fan Main motor SL3 Staple photosensor Document tra y control PCB 10SUB Shading solenoid Lower side Staple LED PCB PS4 VR1 PS1 CL1 M6 M5 Document sensor Document guide width sensor Document tra y HP sensor Registration clutch Document tra y motor Retard motor Fig. 2104 Feed con dition 1 Midd le speed feedi ng, 2 S tandard f eeding, 3 Two doc um ents, 4 No tem porar y stop F eeding of first document is star ted here. F eeding of second document is star ted here. F eeding is stopped. 1 Document tray HP sensor 2 Document tray motor 3 Pickup sensor 4 Front registr ation R sensor 5 Front registr ation L sensor 6 Back registration sensor 7 Pickup motor F eed motor 9 Pickup solenoid 10 Retard motor 11 Registration clutch 12 Main motor Note 1 Black area indicates the activ ating condition and gra y area indicates the condition of sta ying at the present position with the torue dropped down. Note 2 If there is a difference in the timing mark ed, it indicates the occurrence of ske wing. Fig.

<http://dumaxsrl.com/images/bravia-2015-manual.pdf>

2105 The d ocum ent tra y is raise d b y a pres et amount after the doc um ent tray HP sens or is switche d f rom O N to OFF. W hen the docum ent tra y is raised a nd the pick up sens or detects t he doc um ent, the docum ent tray m otor stops and t he main m otor is start ed. W hile the p ick up solenoi d is ON, the pic k up roller re tracts f rom the docum ent. W hen roller desk ew sk ew correcti on is s elected, the doc um ent is pressed ag ainst the regis tratio n roller to p erform sk ew correcti on. After the back registr ation sens or detec ts a doc um ent, the feed m otor stops. Since the pick up sensor is turne d off, no docum ent is detected on the docum ent tra y. After the end of the doc ument pas ses the bac k r egistration s ensor, th e pick up motor, f eed motor, retard m otor and m ain m otor are tur ned OFF a given period of time af ter the sensor detects n o docum ent. The docum ent tra y motor turns in rever se to lo wer the docum ent tray. A given p eriod of tim e after the d ocum ent tra y HP sensor switches from OFF to O N, the docum ent tray m otor is turn ed OFF.

In slow speed feeding, the second document is picked up a given time after both sensors detect no document, after the end of the first document passes the back registration sensor. Thus, the document feeding can maintain specific intervals for high speed, medium speed, and slow speed feeding. Table 2102 The reading system consists of the image reading units and platen rollers. The front reading unit reads the front side of the documents and the back reading unit reads the back side. This configuration enables the unit to read both the front and back sides of a document at one time using a single pass.

These reading units illuminate the document from different directions using two LEDs to prevent shadows, and the analog image data are internally converted to 10bit digital signals and then sent to the image processor on the main CPU PCB. The platen rollers hold the document tightly against the reading glass to keep it in focus. Back platen roller Upper reading roller Front reading unit Document Reading glass Reading glass Front platen roller Lower reading roller Back reading unit Fig. 2201 Therefore, two spacers are attached to the platen rollers outside the image reading area, and the outer diameter of the spacers is a little bit larger than that of the platen rollers. This provides a small gap between the platen rollers and the reading glass when the platen rollers hold the document against the reading glass. Refer to Fig. 2203 Spacer Platen roller Reading glass Spacer Fig. 2203 The valid reading width is 305 mm, and the number of valid pixels is 7260. The optical resolution can be switched between 600 dpi and 300 dpi by an external signal. The main feature of this reading unit is that it provides lighting for the image sensors using two LEDs, lighting the document from both the right and left sides as shown in the figure. The light guides are arranged on the right and left side, and a red R, green G, and blue B LED is arranged for each light guide on the image sensor PCB. LEDs light illuminate the document through the light guides, and the light reflected from the document enters the image sensors through the lens array. The image sensors convert the light to an analog signal. In the binary or grayscale mode, the image is read with composite light generated by lighting all the RGB LEDs simultaneously. In the color mode, the RGB LEDs are sequentially lit, and the image data is read separately for each color.

In the dropout color mode, only the LEDs of the designated color are lit. The shading plate is a white sheet, 0.1 mm thick, housed near the platen roller, and is normally not visible. When shading is performed, the shading solenoid pulls in, so that the shading plate coupled to the gear pops out over the platen roller. The lower shading plate carries out the shading for the front reading unit, and the upper shading plate does the same for the back reading unit. When the shading is completed, the shading plates move back to their original positions. Shading solenoid Upper side Upper shading plate Back reading unit Back platen roller Fig. 2205 2 Shading plate timing The operation of the shading plates is carried out using the timing shown below. a. when the power is on b. after the upper unit is open or closed c. after recovering from power saving mode d. at the beginning of batch processing e. when feeding is started, after no feeding for 10 minutes, during batch to batch processing At the points a, b, and c, LED intensity is adjusted. At d and e, white level adjustment gain adjustment and black level adjustment offsets adjustment are performed according to the LED intensity set at a, b, and c. The LED intensity adjustment is carried out by changing the lighting time of the LED. When the shading plate pops out at points a, b, and c, the LED lighting time under the black and white same for grayscale and color conditions are determined by the reading unit and saved. In this model, the white and black level adjustments are performed by the reading unit for each picture element, and the adjustment value is saved on the sensor drive PCB of the reading unit. The various drive rollers are rotated by motors via gears and timing belts. For controlling the document feed, various sensors are arranged in necessary positions of the system.

The arrangement of the sensors is shown in Fig. 2301, 2302 and 2303. The arms for supporting

the document tray are attached to the four corners of the box unit. The rollers attached at the front ends of the arms are fitted to the document tray. When the arms rotate in a clockwise direction as they are laid down Refer to Fig. 2304, the document tray is raised up. When the arms rotate in a counterclockwise direction as they stand vertically Refer to Fig. 2305, the document tray is lowered. Thus, moving the arms of the box unit enables the raising and lowering of the document tray. Of the four arms, only the two arms fixed to the right end gear shaft are coupled to the gear. Document tray motor Document tray HP sensor Document sensor Document tray Light blocking plate Document Document guide Pickup sensor Pickup roller Arm Arm Box unit Fig. 2304 Arm Arm Fig. 2305 At the same time, the raising of the document tray is stopped. 5 After that, the pickup motor and feed motor are started simultaneously to feed the document. Next, the lowering of the document tray will be explained. 1 When the documents on the document tray run out, the pickup sensor detects no document. 2 After a given time, the document tray motor begins to rotate in reverse. 3 The front and back arms fixed to the right end gear shaft begin to rotate in a counterclockwise direction as they stand vertically. At the same time, the document tray begins to drop down. 4 The light blocking plate moves, switching the document tray HP sensor from OFF to ON, and the document tray is stopped. Since the torque limiter is mounted on the drive transmission assembly of the retard roller, when the friction of the feed roller and the document exceeds the specified value, the retard roller begins to rotate in the same feeding direction as the feed roller. As shown in Fig.

2306 a, when overlapped documents enter into the space between the feed roller and the retard roller, the document in contact with the feed roller is fed in the feeding direction, and the retard roller rotates in the reverse direction so that the document in contact with the retard roller is pushed back wards. As shown in Fig. 2306 b, once a single document remains, the retard roller rotates in conjunction with the feed roller to feed the document. When the Bypass Mode key on the operation panel is pressed, or Manual Feed is selected on the computer, the driving of the feed roller is turned OFF and the retard roller begins to rotate in the forward direction, invalidating the separation function. Feed roller Retard roller Torque limiter a. b. Fig. 2306 As such, it prevents stapled documents from being torn apart. Fig. 2307 shows a stapled document jumping up due to the pickup roller. Pickup roller Staple Documents Fig. 2307 Fig. 2308 shows the configuration of the staple detection. The staple detection consists of staple LEDs and a staple photosensor, arranged on both sides of the document pickup opening. If there is no staple in the documents, the light emitted from the LEDs is received by the photosensor. If the stapled documents jump up, the light gets blocked and the documents are found to be stapled, resulting in stopping the feeding. The five staple LEDs are mounted on the staple LED PCB. Document curl must be 3 mm or less in height and the documents cannot be creased. It is possible to change the level of detection accuracy with the user mode. As shown in Fig. 2309, the front registration sensors consist of the left sensor L and the right sensor R, and are mounted in front of the registration roller. If no skewing occurs, there is no difference in the timing for both sensors detecting the document.

However, if the document is skewed, one of the sensors detects the document earlier and there is a difference in the timing of detecting the document. As the skew amount is increased, the difference is also increased. The difference affects the time of the skew correction performed by the registration roller, and an increased difference will prolong the skew correction time. The time taken from the time both sensors detect the document together until the registration roller begins to rotate is the time required for the skew correction. As shown in Fig. 2310, the skew correction is performed at the registration roller area. When the feed roller feeds the document in the feeding direction, either the right or left front end of the document runs into the registration roller. Since the registration roller remains stopped, the document is turned on the fore end of the document run into the registration roller so that the skew is corrected. Refer

to Fig. 2310 a When the skew correction is performed after both sensors detect the document together, the registration roller begins to rotate and the document is fed without being skewed. Refer to 2310b Feed direction Document Front registration R sensor Front registration L sensor Registration roller Fig. 2309 Feed direction Document Turns this way Registration roller stopped Registration roller rotating a. b. Fig. 2310 The left end sensor is mounted on the left end sensor PCB and the right end sensor is mounted on the right end sensor PCB. When skewing is detected by both sensors, the document feeding is stopped. Feed direction Document Registration roller Right end sensor Left end sensor Fig. 2311 6 Ultrasonic Double Feed Detection Fig. 2312 shows the double feed detection mechanism by ultrasonic.

The double feed detection by ultrasonic uses the ultrasonic transmitting sensor and the ultrasonic receiving sensor. The ultrasonic transmitting sensor is connected to the ultrasonic drive PCB, while the ultrasonic receiving sensor is connected to the ultrasonic sensor PCB. The receiving sensor receives the ultrasonic signal transmitted by the transmitting sensor to gain a specific signal level. When overlapping documents are fed, the signal level is different from when properly feeding a single document. The unit interprets this difference as a double feed and displays an error. Note When the length of the overlapping portion of the documents is less than 50 mm, the double feed may not be detected. Ultrasonic transmitting sensor Ultrasonic receiving sensor Document feed direction Fig. 2312 The front registration sensors are divided into the left sensor L and the right sensor R, and are mounted on the front registration sensor PCB. The back registration sensor is mounted on the back registration sensor PCB. 1 Early reach jam P01 The front edge of the following document was detected after the end of the proceeding document is detected before the motor finishes driving the specified length. 2 Residual jam P02 The end of the document is not detected even though the document has been fed for a specific length after the front edge was detected. 3 Fast feed jam P03 The end of the document is detected before the document has been fed for a specific length after the front edge was detected. This mode should not be available to the users. The mechanical feed mode can be activated by pressing the keys on the operation panel, as follows a. Turn on the power switch with the start key pressed. b. Continue pressing the start key for about one second. c. Press the stop key.

If the start key is pressed while in the mechanical feed mode, with documents in the document tray, the machine will feed the documents at a feed speed determined by the SCSI ID set on the DIP switch located at the computer connection. Table 2301 Table 2401 lists the function of each IC shown in the block diagram. Table 2401 For example, when the resolution set in the personal computer is 300 dpi or less 300, 240, 200, 150, 100, the optical resolution of the unit is set to 300 dpi. And, when 400 dpi or 600 dpi is set on the computer side, 600 dpi is set on the reading unit side. However, since the software is not available for the earlier model, both processors serve to conduct the processing of image data. A multi-stream function can output different modes of data from a single scan. The description below describes the image processing in the earlier model where the multistream function is not available. Image resolution conversion is carried out by image processor 1. For converting resolution, one of two methods, thinning out and smoothing, is used according to the image mode. The smoothing process also helps to reduce moiré patterns. Image processor 2 handles brightness adjustment, contrast adjustment, and gamma correction. Image processor 3 handles edge emphasis, simple binarizing, error diffusion, and automatic brightness adjustment. The automatic brightness adjustment is valid for simple binary mode. In the JPEG module, the grayscale and color data can be compressed. When JPEG is selected, the image data size is reduced by compression within this machine so that it can be transferred to the personal computer in less time. As a result, more documents can be scanned in a given time. Finally, processed image data are sent from the DMA controller to the computer either through the SCSI or USB interface.

Other image processing is carried out on the personal computer. After the rearrangement, the data would be "R1, G1, B1, R2, G2, B2, R3, G3, B3, R4, G4, B4, R5, G5, B5". R1 R2 G1 G2 B1 B2 R N G N B N R1 G1 B1 R2 R N G N B N G2 B2 a. Data output b. RGB rearrangement 1st pixel 2nd pixel Nth pixel Fig. 2502 The resolution in the main scanning direction is the same as in the subscanning direction. The optical resolution main scanning direction of the reading unit can be switched between 600 and 300 dpi. Therefore, when 400 dpi is selected, the resolution is converted from 600 dpi, and when 240 dpi or less is selected, it is converted from 300 dpi. When converting to 240 dpi, 1 clock pulse is removed from every 5 pulses. And, when converting to 400 dpi, the standard 600 dpi clock is used with 1 clock removed from every 3 clock pulses.

123456789 1 0 11 12 34 56 78 300 dpi standard clock 300 dpi image data 200 dpi operating clock 200 dpi image data Fig. 2503 In the case of 150 dpi, it is twice the speed, and in the case of 100 dpi, three times the speed used for 300 dpi. Since the timing for reading the data from the image sensor CIS is the same, the resolution in the subscanning direction can be converted by changing the feed speed. Refer to Fig. 2504 a For low resolution binary and grayscale modes the original data for both is grayscale, the feed speed must be raised excessively high. The feed speed can be increased by raising the motor speed. For grayscale mode, smoothing is always performed because the number of scanned documents is not decreased even by smoothing. For color mode, Smoothing can be selected by the user. When the optical resolution of the reading unit is 600 dpi or 300 dpi, smoothing to 600 dpi or 300 dpi is not carried out.

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